

# Modelling and control summaries



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## USE OF MATLAB 1 – solving ODEs

**OVERVIEW:** These notes gives a very narrow view of MATLAB and thus demonstrate how to do a limited number of things. In general students are encouraged to become flexible independent learners using the provided MATLAB helps as this is a widely required skill in industry.

**SOLVING ODEs:** This note will consider only ODEs with constant coefficients and also only demonstrates 1<sup>st</sup> and 2<sup>nd</sup> order.

$$A \frac{dx}{dt} + Bx = f(t); \quad x(0) = x_0$$

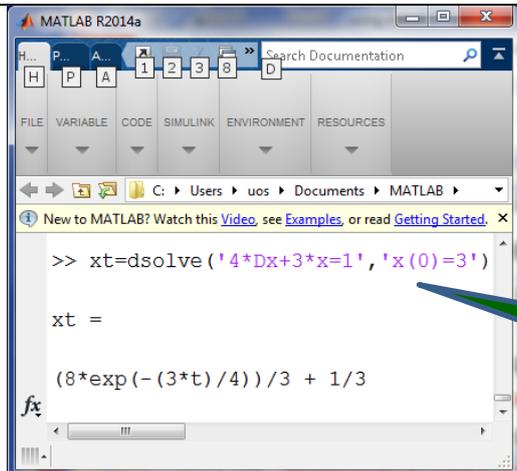
$$A \frac{d^2x}{dt^2} + B \frac{dx}{dt} + Cx = f(t); \quad x(0) = x_0; \quad \dot{x}(0) = \dot{x}_0$$

1. How do I use MATLAB to find an analytic solution? [**Covered here**]
2. How do I use MATLAB to find a numerical solution and thus one I can plot? [**Cover elsewhere**]

**ANALYTIC SOLUTIONS:** These make use of the symbolic toolbox so you need to be sure you have this. (Type help in the command window and a list of available toolboxes will be listed)

The BASIC MATLAB command is **dsolve**. Students need to learn how to enter their ODE in the required format. This is best illustrated by a number of examples.

$4 \frac{dx}{dt} + 3x = t^2 + \cos t; \quad x(0) = 3$	<code>xt=dsolve('4*Dx+3*x=t^2+cos(t)','x(0)=3')</code>	
$4 \frac{dx}{dt} + 3x = 1; \quad x(0) = 3$	<code>xt=dsolve('4*Dx+3*x=1','x(0)=3')</code>	Note that any 'multiply' is explicit.
$4 \frac{dx}{dt} + 3x = 1; \quad x(1) = 2$	<code>xt=dsolve('4*Dx+3*x=1','x(1)=2')</code>	Initial condition



Solution

ODE in required format (inside quotes)

Initial condition

Note how colour changes to indicate a correct formatting.

**MORE ADVANCED USE:** What if not all initial conditions are known or if the ODE coefficients are not known? These can be replaced by symbolic variables and **dsolve** will still work.

$$T \frac{dy}{dt} + ky = 1; \quad y(0) = y_0$$

Create symbolic variables as required

Use symbolic variables in the dsolve command.

Solution in terms of the unknowns

```

>> syms k T y0
>> yt=dsolve('T*Dy+k*y=1','y(0)=y0')

yt =

(exp(-(k*t)/T)*(k*y0 - 1) + 1)/k
    
```

**Second order ODE:** These are demonstrated by example and use the equivalent syntax to 1<sup>st</sup> order, but you need 2 initial conditions to get a full solution.

The BASIC MATLAB command is **dsolve**. Students need to learn how to enter their ODE in the required format. This is best illustrated by a number of examples.

$$2 \frac{d^2x}{dt^2} + 6 \frac{dx}{dt} + 4x = 1$$

xt=dsolve('2\*D2x+6\*Dx+4\*x=1')  
NO INITIAL CONDITIONS PROVIDED so solution has underdetermined coefficients.

$$2 \frac{d^2x}{dt^2} + 6 \frac{dx}{dt} + 4x = 1; \quad \begin{matrix} x(0) = 1 \\ \dot{x}(0) = 0 \end{matrix}$$

xt=dsolve('2\*D2x+6\*Dx+4\*x=1','x(0)=1','Dx(0)=0')

Students should notice the syntax adopted by MATLAB of

D2x to represent  $d^2x/dt^2$  and Dx to represent  $dx/dt$

Equivalently students can use D2z for  $d^2z/dt^2$  and so forth – see example below.

```

>> xt=dsolve('2*D2x+6*Dx+4*x=1','x(0)=1','Dx(0)=0')

xt =

fx (3*exp(-t))/2 - (3*exp(-2*t))/4 + 1/4
    
```

**A 3<sup>rd</sup> order example** is given to demonstrate the basic principle and notation extends.

$$2 \frac{d^3z}{dt^3} + 2 \frac{d^2z}{dt^2} + 6 \frac{dz}{dt} + 4z = \sin(t); \quad \begin{matrix} z(0) = 1 \\ \dot{z}(0) = 0 \\ \ddot{z}(0) = 1 \end{matrix}$$

zt=dsolve('2\*D3z+2\*D2z+6\*Dz+4\*z=sin(t)','z(0)=1','Dz(0)=0','D2z(0)=1')