

Modelling and control summaries



by Anthony Rossiter

Bode 18: bandwidth

	<p>SUMMARY of Frequency response</p> $u = D\sin(\omega t) \Rightarrow y = DA\sin(\omega t + \phi)$ <ol style="list-style-type: none"> Gain $A(\omega)$ is the ratio of output amplitude of oscillation to that of the input. Phase $\phi(\omega)$ is the phase difference between the input and output responses.
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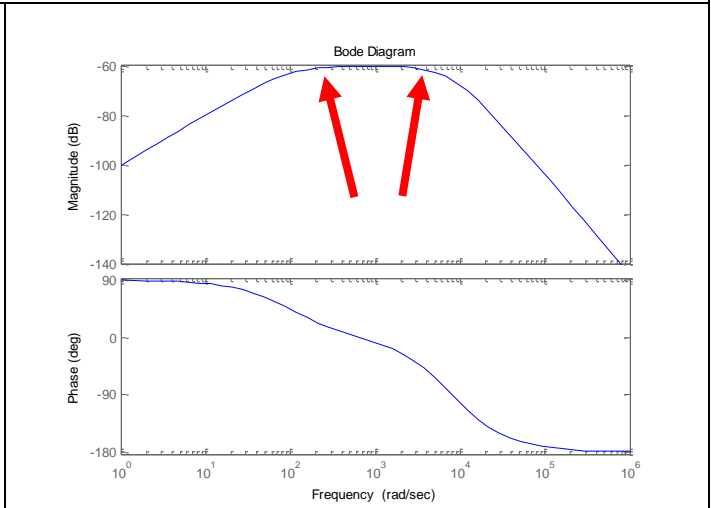
What is bandwidth?	
<p>Typically, bandwidth is the range of frequencies for which gain A is significant. However this is not precise enough.</p> <p>Is significant relative to steady-state gain or relative to 0dB (gain of 1)? As seen here these alternatives give very different values of frequency.</p> <p>A common default is that bandwidth is frequency range where gain > 1/√2 (or -3dB). Use with caution!</p>	

EXAMPLE of a SPEAKER

Clearly, the speaker gives a consistent reproduction for a limited range of frequencies (about 100-3000rad/s) as marked in the figure.

$$G = \frac{2.5 s}{4e-005 s^3 + 0.604 s^2 + 2554 s + 250000}$$

NOTE: The actual gain here is -60dB, so not close to 0dB!



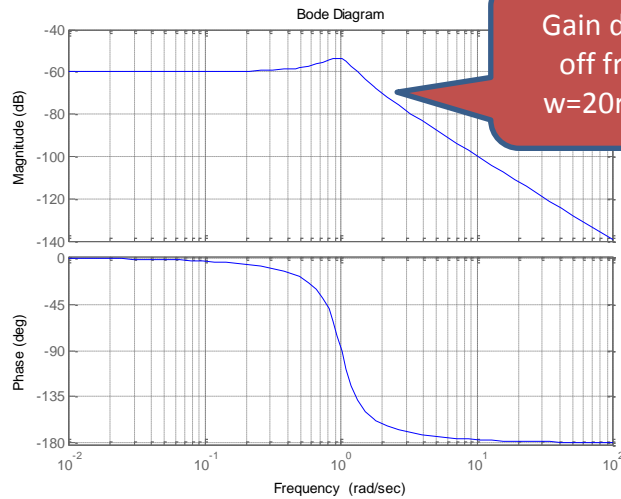
A suspension system is designed to reject high frequency disturbances (those beyond 50 rad/s). Comment on the efficacy of the unit.

$$G = \frac{s}{Ms^2 + Bs + k};$$

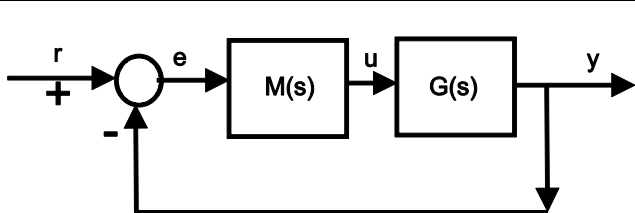
$$M = 10^3; B = 500;$$

$$k = 10^3$$

Clearly for frequencies above 20rad/s, the gain is down by more than 10dB from steady-state so fit for purpose.



Bandwidth with feedback control systems



In a typical feedback loop, the desired closed-loop gain (steady-state) is unity, that is the output tracks the target.

$$y = \frac{GM}{1+GM} r = G_c r; \quad E[G_c(0)] = 1$$

A meaningful definition of bandwidth is where the gain is greater than 1/√2 (or -3dB)

Bandwidth with open-loop or closed-loop Bode diagrams

1. While one can use software to plot the closed-loop Bode, most design is based on the open-loop Bode and hence it is convenient to estimate closed-loop bandwidth from the open-loop Bode diagram.
2. Gain cross-over frequency is where the open-loop Bode is 0dB.
3. For a good design, the phase is about -120° at the gain cross-over frequency.

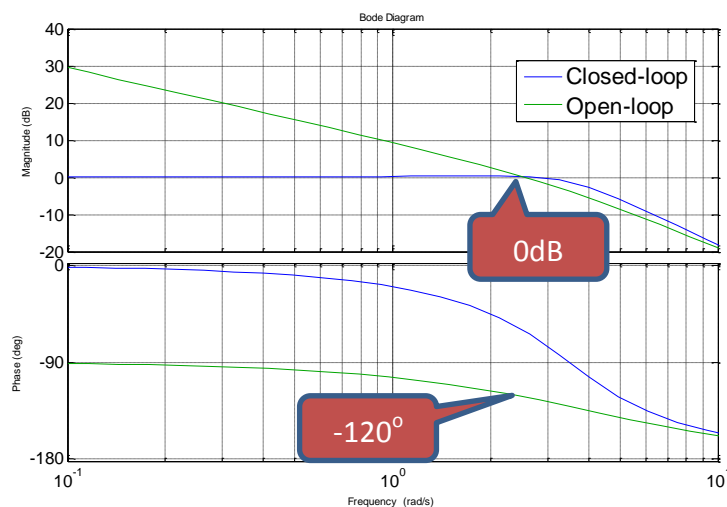
Substituting in the expected value of GM at the gain cross-over frequency one finds the open and closed-loop are close to 0dB at the same frequency.

$$GM \approx (-1 - j\sqrt{3})/2 = 1 \angle -120^\circ$$

$$\Rightarrow (1 + GM) = (1 - j\sqrt{3})/2$$

$$\Rightarrow |1 + GM| = |GM|$$

$$\Rightarrow \left| \frac{GM}{1 + GM} \right| = 1 \quad (0dB)$$



A helpful approximation to closed-loop bandwidth is the gain cross over frequency.