

# Modelling and control summaries



by Anthony Rossiter

## Nyquist 13: Applying stability criteria

The full definition of a Nyquist diagram is the mapping of  $G(s)$  while  $s$  describes the D-contour. A system is closed-loop stable ( $n_c$ =number RHP closed-loop poles) if and only if the number of counter-clockwise encirclements of -1 point matches number  $n_o$  of open-loop RHP poles.

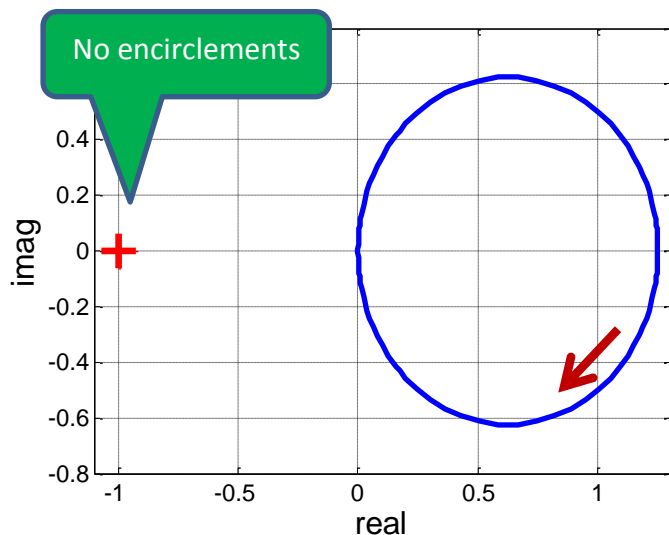
**Alternatively, apply  $n_q = n_c - n_o$  directly or  $n_c = n_q + n_o$**

### Apply Nyquist stability criteria to numerous examples

$$G = \frac{5}{s+4};$$

$$\left. \begin{matrix} n_o = 0 \\ n_q = 0 \end{matrix} \right\} \Rightarrow n_c = 0$$

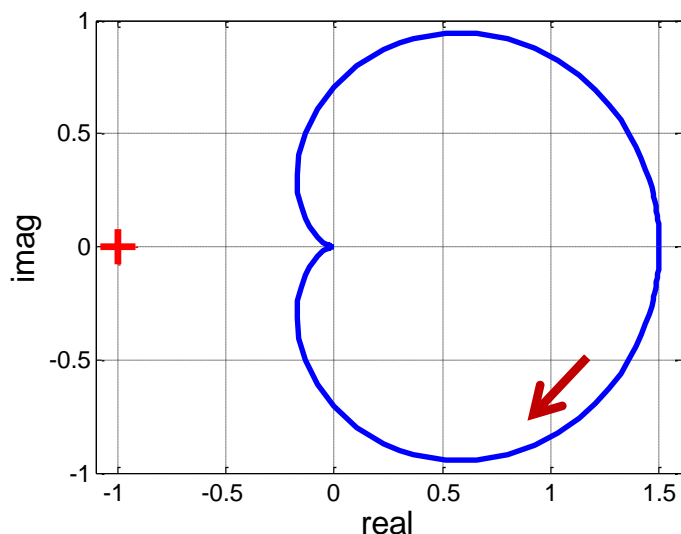
CLOSED-LOOP STABLE (For all +ve K)

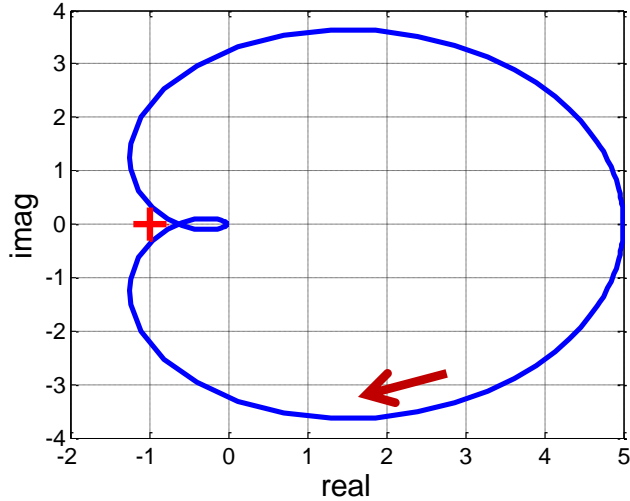
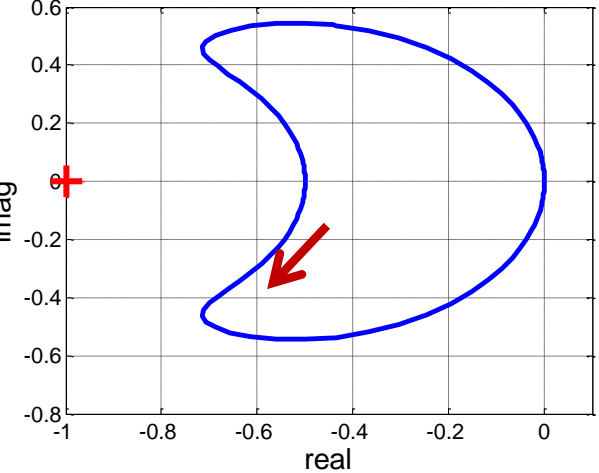
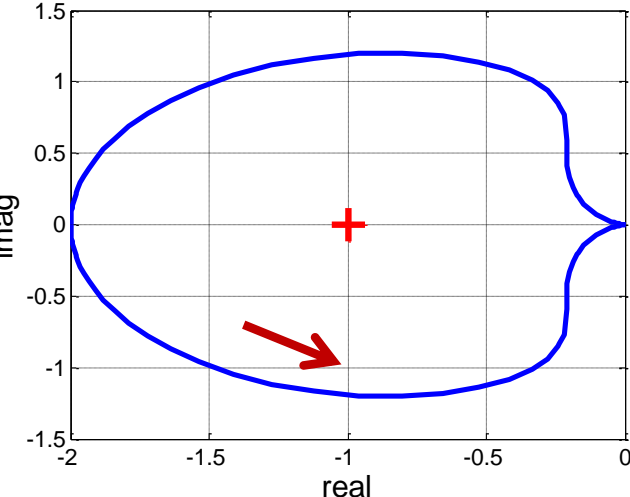


$$G = \frac{3}{(s+2)(s+1)};$$

$$\left. \begin{matrix} n_o = 0 \\ n_q = 0 \end{matrix} \right\} \Rightarrow n_c = 0$$

CLOSED-LOOP STABLE (For all +ve K)



$G = \frac{5}{(s+1)^3}; \quad K = 1$ $\left. \begin{array}{l} n_o = 0 \\ n_q = 0 \end{array} \right\} \Rightarrow n_c = 0$ <p>Clearly stable for current K.</p> <p>However, <math>K &gt; 8/5</math> implies that <math>n_q = 2</math> and hence one will have <math>n_c = 2</math>, that is closed-loop instability.</p>	
$G = \frac{s+0.1}{(s+0.2)(s-1)}; \quad K = 1$ $\left. \begin{array}{l} n_o = 1 \\ n_q = 0 \end{array} \right\} \Rightarrow n_c = 1$ <p>Clearly <b>unstable</b> for current K (a closed-loop RHP pole).</p> <p>However, <math>K &gt; 2</math> implies that <math>n_q = -1</math> and hence one will have <math>n_c = 0</math>, that is closed-loop stability.</p>	
$G = \frac{40(s+2)}{(s+10)(s+4)(s-1)};$ $\left. \begin{array}{l} n_o = 1 \\ n_q = -1 \end{array} \right\} \Rightarrow n_c = 0$ <p>Clearly stable for current <math>K=1</math>.</p> <p>However, <math>K &lt; 0.5</math> will remove the counter clockwise encirclement and hence closed-loop instability would follow.</p>	

**REMARKS** The result is based on two things which students must be skilled at:

1. Counting open-loop RHP poles – a common mistake is to forget the distinction between LHP and RHP poles. Only count open-loop RHP poles. This is  $n_o$ .
2. Sketch the Nyquist diagram of the loop transfer function and count encirclements of the -1 point. This is  $n_q$ .

Determine the number of RHP closed-loop poles from  $n_c = n_q + n_o$ .