

# Modelling and control summaries



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## Root-loci 17: Angles of arrival/departure

The focus is on the simplest form of block diagram, a process  $G(s)$  and a compensator  $M(s)$  which is expressed as a gain  $K$  multiplied by a transfer function. The closed-loop transfer function is  $G_c(s)$ .

	<p style="color: red; font-weight: bold;">Conditions for closed-loop poles</p> $p_c = 0 \equiv \left\{ \begin{array}{l} Kn + d = 0 \\ K \frac{n}{d} = -1 \\ \arg\left(\frac{n}{d}\right) = \pm 180^\circ \end{array} \right\}$
$M(s) = K\tilde{M}(s)$	$G_c = \frac{GK\tilde{M}}{1 + GK\tilde{M}} = \frac{Kn}{Kn + d}$

Complex poles or zeros	
<p>When a system has complex conjugate pairs of poles or zeros, these serve as departure or arrival points for the loci. A key question <b>linked to design</b> is to determine from what direction the loci approach these positions.</p> <div style="border: 2px solid red; border-radius: 15px; background-color: red; color: white; padding: 10px; display: inline-block; margin-top: 20px;"> <p style="margin: 0;">At what angle does loci approach this zero?</p> </div>	

How to determine angles of arrival and departure	
<p>Use the angle criteria for a candidate value 's' near the relevant pole/zero, that is:</p> $\angle n - \angle d = \pm 180^\circ$	$n = (s - z_1)(s - z_2) \cdots (s - z_m) \Rightarrow \angle n = \sum \angle (s - z_i)$ $d = (s - p_1)(s - p_2) \cdots (s - p_k) \Rightarrow \angle d = \sum \angle (s - p_i)$ $\sum \angle (s - z_i) - \sum \angle (s - p_i) = \pm 180^\circ$

### Using approximation

If  $s$  (on loci) is very close to  $z_i$ , then one can approximate most of the angles by writing  $s=z_i$ .

$$\sum_{j \neq i} \angle(z_i - z_j) + \angle s - z_i - \sum \angle(z_i - p_j) = \pm 180^\circ$$

Rearranging the above equation we find the angle of arrival/departure directly.

$$\angle s - z_i = -\sum_{j \neq i} \angle(z_i - z_j) + \sum \angle(z_i - p_j) \pm 180^\circ$$

### Example of using approximation

$$G = \frac{(s+1+j)(s+1-j)}{s(s+2)(s+1)}$$

$$z_1 = -1+j, z_2 = -1-j$$

$$p_1 = 0, p_2 = -1, p_3 = -2$$

Find angle of arrival at  $z_1$ .

Using formulae above, substitute in  $z_i, p_j$ :

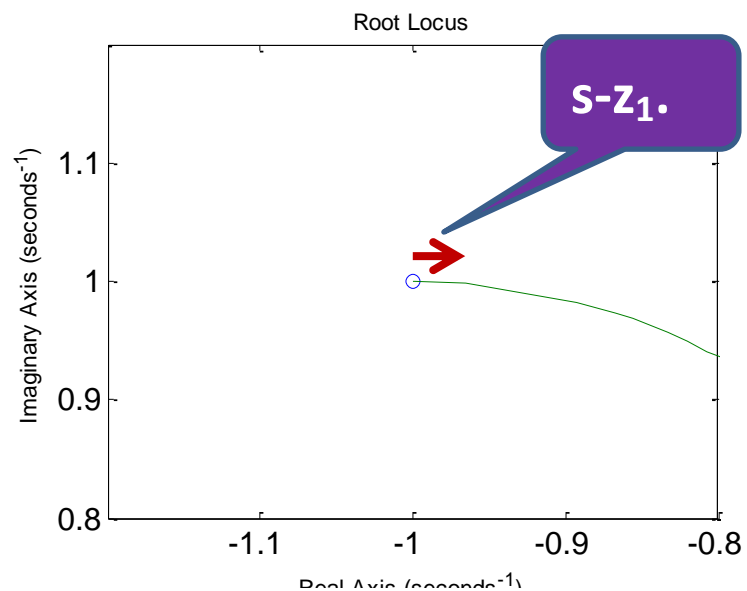
$$\angle s - z_1 = -\angle[(-1-j) - (-1+j)] + \angle[(-1-j) - (0)] + \angle[(-1-j) - (-1)] + \angle[(-1-j) - (-2)] \pm 180^\circ$$

Hence:

$$\angle s - z_1 = -\angle -2j + \angle(-1-j) + \angle -j + \angle(1-j) \pm 180^\circ$$

$$\angle s - z_1 = 90 + (-135) - 90 - 45 \pm 180^\circ = 0^\circ$$

A blow up of the root locus near  $z_1$  shows that the loci does indeed approach in the direction given, that is 0 degrees!



**REMARKS:** Calculating angles of arrival and departure is quite tedious by hand and in the days of modern computing it would be rare to do this. However, understanding the procedure can give some useful insight that helps with design.