

Modelling and control summaries



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1st order responses 4: Sketching

Assume a standard **time constant form** for a 1st order model with constant coefficients, output $y(t)$ and constant input $u(t)$.

$$\left\{ \begin{array}{l} T \frac{dx}{dt} + x = Ku(t) \\ u(t) = A, t \geq 0 \end{array} \right\} \Rightarrow x(t) = KA(1 - e^{-\frac{t}{T}}) + x(0)e^{-\frac{t}{T}} = KA + (x(0) - KA)e^{-\frac{t}{T}}$$

steady-state

Distance from steady-state

COMPUTE the values at integer multiples of the time constant using fractions of the initial distance from steady-state $d = x(0) - KA$

$$\begin{aligned} x(T) &= KA + d \times 0.37 \\ x(2T) &= KA + d \times 0.14 \\ x(3T) &= KA + d \times 0.05 \end{aligned}$$

Moved 63% in one time constant (or 37% still to go).

Only 5% from steady-state after 3 time constants.

BASIC TECHNIQUE: Mark the values $x(0)$, $x(T)$, $x(3T)$ and the steady-state and draw a smooth line between these.

EXAMPLE 1 (Assuming that the input is a unit step)

$$\begin{aligned} 2 \frac{dx}{dt} + 6x &= 4u \Rightarrow T = \frac{1}{3}, \quad KA = \frac{4}{6} \\ u(t) &= 1, \quad x(0) = -1 \end{aligned}$$

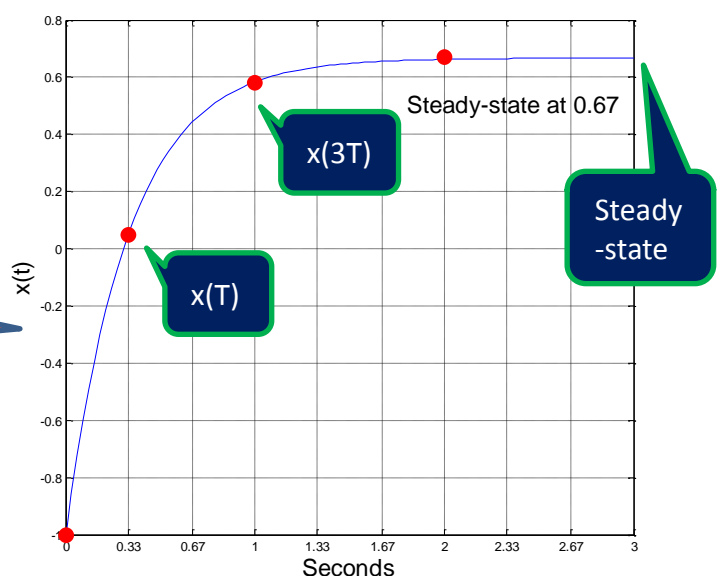
PRELIMINARY STEPS

1. Steady-state is $2/3$
2. Initial offset $d = x(0) - KA = -5/3$

Compute $x(T)$ and $x(3T)$.

$$\begin{aligned} x(T) &= KA + d \times 0.37 = \frac{2}{3} - 0.37 \times \frac{5}{3} = 0.05 \\ x(3T) &= KA + d \times 0.05 = \frac{2}{3} - 0.05 \times \frac{5}{3} = 0.58 \end{aligned}$$

Place data on curve and join by a smooth curve.



IMPROVING SKETCH WITH A GRADIENT

The initial gradient can be computed by inspection and thus added to ensure the sketch is more accurate. **NO computation is needed!**

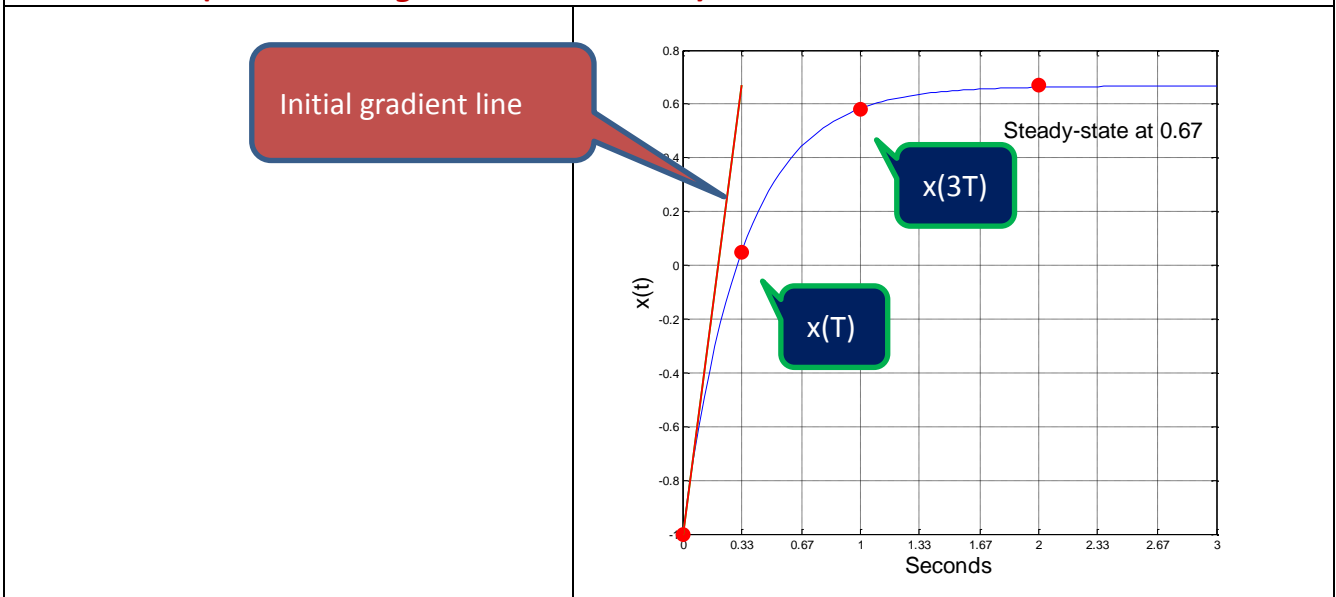
At $t=0$, find the gradient using simple differentiation.

$$\left. \begin{aligned} x &= (x(0) - KA)e^{-\frac{t}{T}} + KA \\ \frac{dx}{dt} &= \frac{(x(0) - KA)}{-T} e^{-\frac{t}{T}} \end{aligned} \right\} \Rightarrow \frac{dx}{dt}(0) = \frac{KA - x(0)}{T} = \frac{-d}{T}$$

A straight line through the point $[0, x(0)]$ with this gradient will also go through the point $[T, x(0) - d] = [T, KA]$

Add this line to the plot before doing the sketch. **[GET TO STEADY-STATE IN ONE TIME CONSTANT]**

EXAMPLE 1 (With initial gradient line added)



REVERSE COMPUTATIONS: Estimate time constant T and gain K from the step response for input of magnitude A using the two observations:

1) Steady-state is KA and 2) time to move 63% of way to steady-state is T (or 37% from KA).

- Total move is $-1.5 \rightarrow 0.8$ or 2.3 up.
- $x(T) = 0.9 - 0.37 * 2.3 = -0.05$

- Total move is $25 \rightarrow 5$ or 20 down.
- $x(T) = 5 - 0.37 * (-20) = 12.4$

