

Modelling and control summaries



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2nd order responses 1: over-damped systems

Assume a standard 2nd order model with constant coefficients, output $y(t)$ and input $u(t)$. What is the expected behaviour and how does this vary with a, b, c ?

$$a \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + cx = f$$

For now the focus is on constant f , usually $f=0$ or $f=1$.

An overdamped system is where the characteristic polynomial marked below has real roots

$$a \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + cx = f \Rightarrow \textcircled{ap^2 + bp + c = 0} \Rightarrow p = p_1, p_2$$

Real roots p_1, p_2 implies that $b^2 > 4ac$.
This means that, for constant f , the solution takes the following form:

$$x(t) = Ae^{p_1 t} + Be^{p_2 t} + \frac{f}{c}$$

What remains is to determine the unknown coefficients A, B .

Response with zero initial conditions ($x(0)=0, dx/dt(0)=0$)

Substitute the known solution from above into the two initial conditions and this gives simultaneous equations in A and B .

$$\begin{cases} x(t) = Ae^{p_1 t} + Be^{p_2 t} + \frac{1}{c} \\ \dot{x}(t) = p_1 Ae^{p_1 t} + p_2 Be^{p_2 t} \end{cases} \Rightarrow \begin{cases} x(0) = 0 = A + B + \frac{1}{c} \\ \dot{x}(0) = 0 = p_1 A + p_2 B \end{cases}$$

$$\{0 = p_1 A + p_2 B\} \Rightarrow \left\{ A = \frac{-p_2}{p_1} B \right\}; \quad \left(\frac{p_2}{p_1} - 1 \right) B = \frac{1}{c}; \quad A = \frac{-p_2}{c(p_2 - p_1)}; \quad B = \frac{p_1}{c(p_2 - p_1)}$$

Response includes two exponentials.

1. The exponential with the slowest time scale (larger p_i) has the largest coefficient.
2. If $p_2 \gg p_1$, then the response can be approximated by the slower exponential only.

$$x = \frac{1}{c} \left[1 + \left(\frac{1}{p_2 - p_1} \right) (p_1 e^{p_2 t} - p_2 e^{p_1 t}) \right]$$

EXAMPLE 1

$$\ddot{x} + 3\dot{x} + 2x = 1$$

$$p^2 + 3p + 2 = 0$$

$$\Rightarrow p_1 = -1, p_2 = -2$$

Plug in the solution from above.

$$x = \frac{1}{c} \left[1 + \left(\frac{1}{p_2 - p_1} \right) (p_1 e^{p_2 t} - p_2 e^{p_1 t}) \right]$$

$$p_1 = -1, \quad p_2 = -2, \quad c = 2$$

$$x = \frac{1}{2} \left[1 + \left(\frac{1}{-1} \right) (-e^{-2t} + 2e^{-t}) \right]$$

EXAMPLE 2

$$\ddot{x} + 8\dot{x} + 7x = 14$$

$$p^2 + 8p + 7 = 0$$

$$\Rightarrow p_1 = -7, p_2 = -1$$

Plug in the solution from above.

$$x = \frac{14}{c} \left[1 + \left(\frac{1}{p_2 - p_1} \right) (p_1 e^{p_2 t} - p_2 e^{p_1 t}) \right]$$

$$p_1 = -7, \quad p_2 = -1, \quad c = 7$$

$$x = \frac{14}{7} \left[1 + \left(\frac{1}{-1+7} \right) (-7e^{-t} + e^{-7t}) \right]$$

Note that slower mode is dominating

REMARK

With non-zero initial conditions the solution will not have such a simple generic solution. However, such scenarios with more involved algebra, offer little useful insight so are not pursued here.